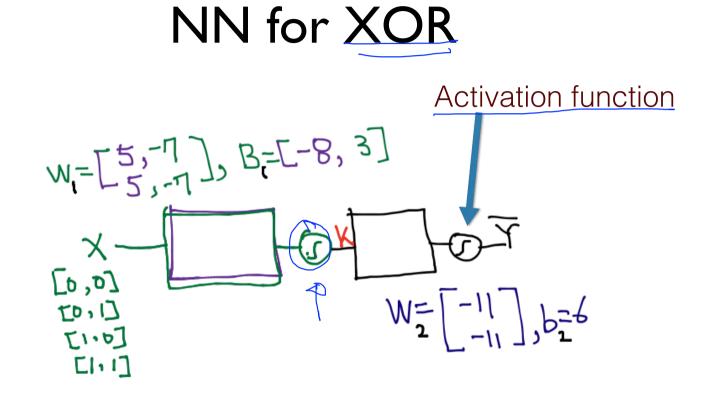
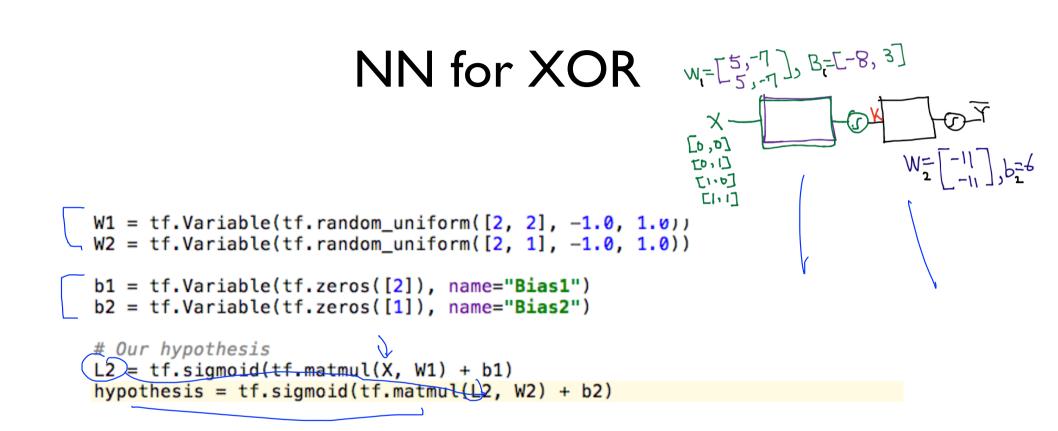
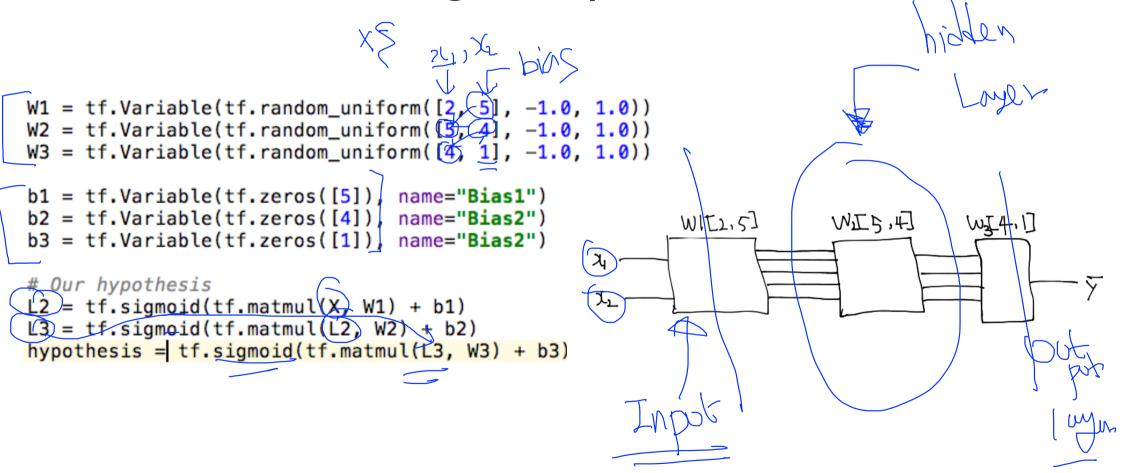
Lecture 10-1 ReLU: Better non-linearity

Sung Kim <hunkim+mr@gmail.com> http://hunkim.github.io/ml/





Let's go deep & wide!



9 hidden layers!

W1 = tf.Variable(tf.random_uniform(\[2, 5], -1.0, 1.0), name = "Weight1") W2 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight2") W3 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight3") W4 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight4") W5 = tf.Variable(tf.random_uniform([5,,5], -1.0, 1.0), name = "Weight5") W6 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight6") W7 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight7") W8 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight8") W9 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight9") W10 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight10") W11 = tf.Variable(tf.random_uniform([5, [1], -1.0, 1.0), name_=_"Weight11") b1 = tf.Variable(tf.zeros([5]), name="Bias1") b2 = tf.Variable(tf.zeros([5]), name="Bias2") b3 = tf.Variable(tf.zeros([5]), name="Bias3") b4 = tf.Variable(tf.zeros([5]), name="Bias4") b5 = tf.Variable(tf.zeros([5]), name="Bias5") b6 = tf.Variable(tf.zeros([5]), name="Bias6") b7 = tf.Variable(tf.zeros([5]), name="Bias7") b8 = tf.Variable(tf.zeros([5]), name="Bias8") b9 = tf.Variable(tf.zeros([5]), name="Bias9") b10 = tf.Variable(tf.zeros([5]), name="Bias10")

b11 = tf.Variable(tf.zeros([1]), name="Bias11")

9 hidden layers!

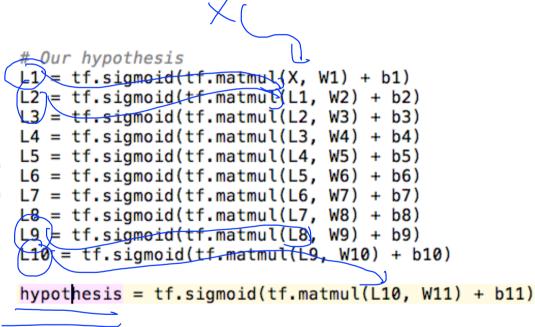
```
W1 = tf.Variable(tf.random_uniform([2, 5], -1.0, 1.0), name_=_"Weight1")
```

```
W2 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight2")
W3 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight3")
W4 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight4")
W5 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight5")
W6 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight6")
W7 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight6")
W8 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight6")
W8 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight8")
W9 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight9")
W10 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight10")
```

```
W11 = tf.Variable(tf.random_uniform([5, 1], -1.0, 1.0), name_=_"Weight11")
```

b1 = tf.Variable(tf.zeros([5]), name="Bias1") b2 = tf.Variable(tf.zeros([5]), name="Bias2") b3 = tf.Variable(tf.zeros([5]), name="Bias3") b4 = tf.Variable(tf.zeros([5]), name="Bias4") b5 = tf.Variable(tf.zeros([5]), name="Bias5") b6 = tf.Variable(tf.zeros([5]), name="Bias6") b7 = tf.Variable(tf.zeros([5]), name="Bias7") b8 = tf.Variable(tf.zeros([5]), name="Bias8") b9 = tf.Variable(tf.zeros([5]), name="Bias9") b10 = tf.Variable(tf.zeros([5]), name="Bias10")

```
b11 = tf.Variable(tf.zeros([1]), name="Bias11")
```



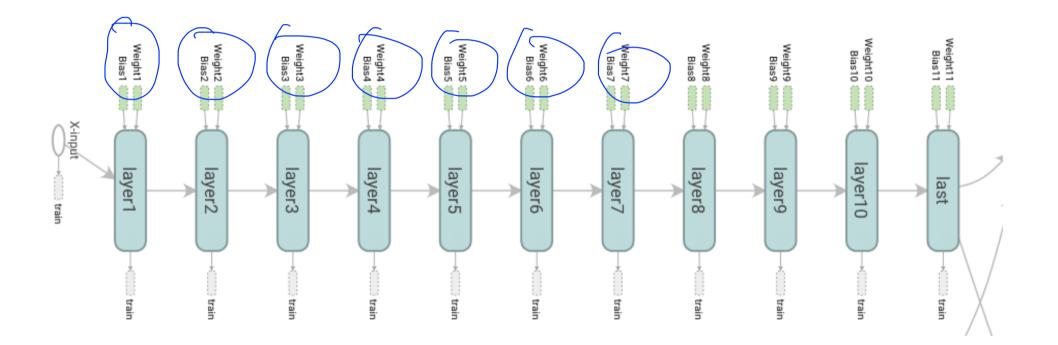
9 hidden layers!

```
W1 = tf.Variable(tf.random uniform([2, 5], -1.0, 1.0), name = "Weight1")
W2 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight2")
W3 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight3")
W4 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight4")
W5 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight5")
W6 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight6")
W7 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight7")
W8 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight8")
W9 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight9")
W10 = tf.Variable(tf.random_uniform([5, 5], -1.0, 1.0), name = "Weight10")
W11 = tf.Variable(tf.random_uniform([5, 1], -1.0, 1.0), name = "Weight11")
b1 = tf.Variable(tf.zeros([5]), name="Bias1")
b2 = tf.Variable(tf.zeros([5]), name="Bias2")
b3 = tf.Variable(tf.zeros([5]), name="Bias3")
b4 = tf.Variable(tf.zeros([5]), name="Bias4")
b5 = tf.Variable(tf.zeros([5]), name="Bias5")
b6 = tf.Variable(tf.zeros([5]), name="Bias6")
b7 = tf.Variable(tf.zeros([5]), name="Bias7")
b8 = tf.Variable(tf.zeros([5]), name="Bias8")
b9 = tf.Variable(tf.zeros([5]), name="Bias9")
b10 = tf.Variable(tf.zeros([5]), name="Bias10")
b11 = tf.Variable(tf.zeros([1]), name="Bias11")
```

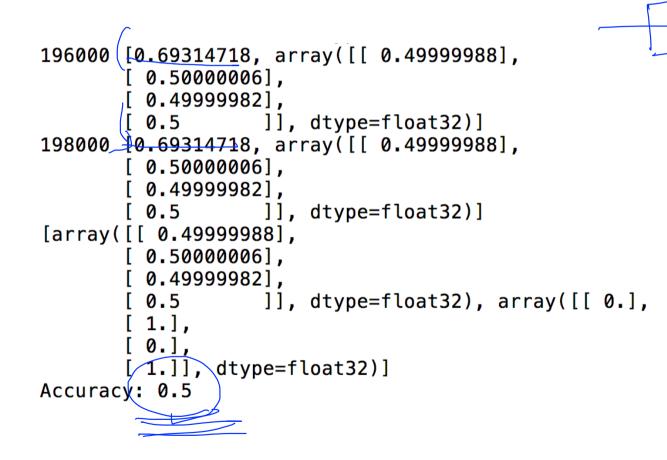
Our hypothesis with tf.name_scope(\'layer1")_as_scope: Γ L1 = tf.sigmoid(tf.matmul(X, W1) + b1) with tf.name scope("layer2") as scope: L2 = tf.sigmoid(tf.matmul(L1, W2) + b2)with tf.name_scope("layer3") as scope: L3 = tf.sigmoid(tf.matmul(L2, W3) + b3)with tf.name_scope("layer4") as scope: U4 = tf.sigmoid(tf.matmul(L3, W4) + b4)with tf.name_scope("layer5") as scope: L5 = tf.sigmoid(tf.matmul(L4, W5) + b5)with tf.name_scope("layer6") as scope: L6 = tf.sigmoid(tf.matmul(L5, W6) + b6)with tf.name_scope("layer7") as scope: L7 = tf.sigmoid(tf.matmul(L6, W7) + b7)with tf.name_scope("layer8") as scope: L8 = tf.sigmoid(tf.matmul(L7, W8) + b8)with tf.name scope("layer9") as scope: L9 = tf.sigmoid(tf.matmul(L8, W9) + b9)with tf.name_scope("layer10") as scope: L10 = tf.sigmoid(tf.matmul(L9, W10) + b10)with tf.name scope("last") as scope:

```
hypothesis = tf.sigmoid(tf.matmul(L10, W11) + b11)
```

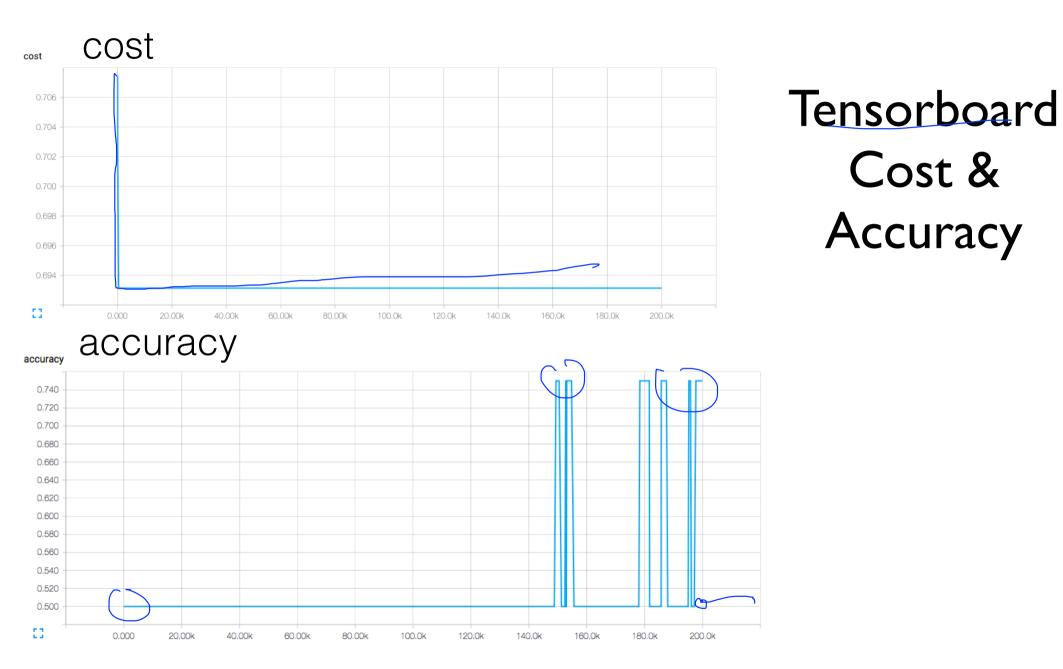
Tensorboard visualization

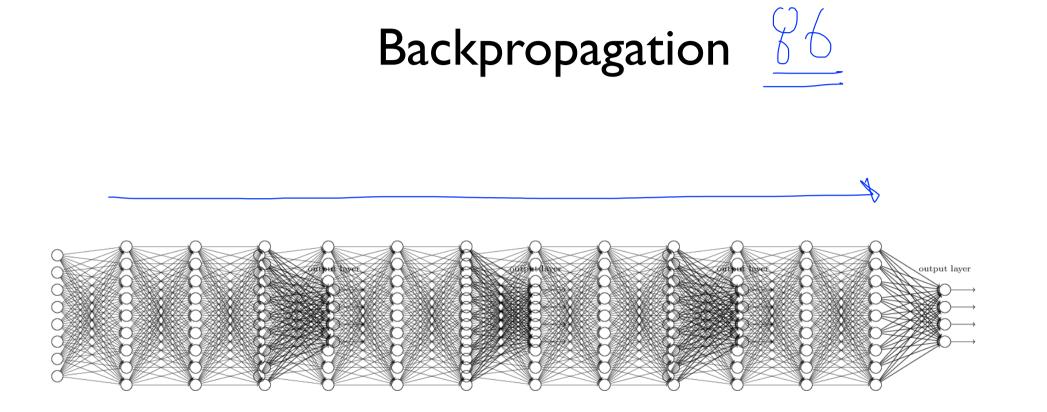


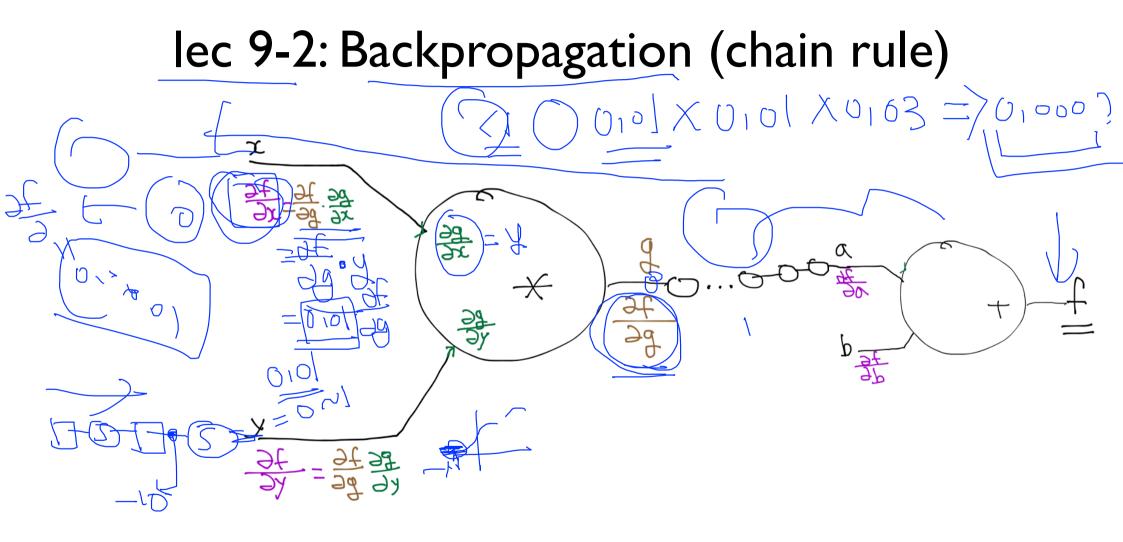
Poor results?





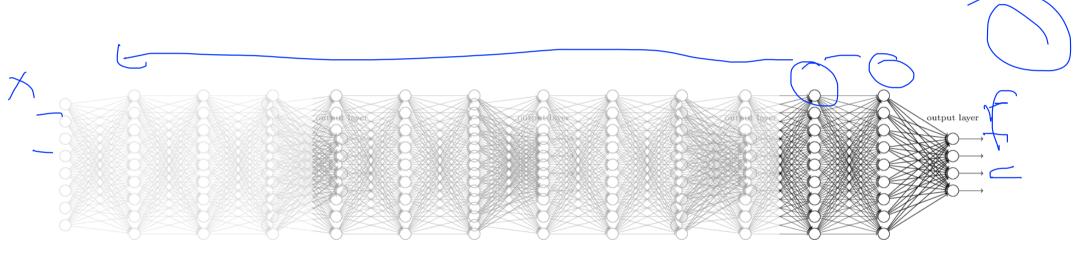


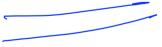




http://cs231n.stanford.edu/

Vanishing gradient (NN winter2: 1986-2006)

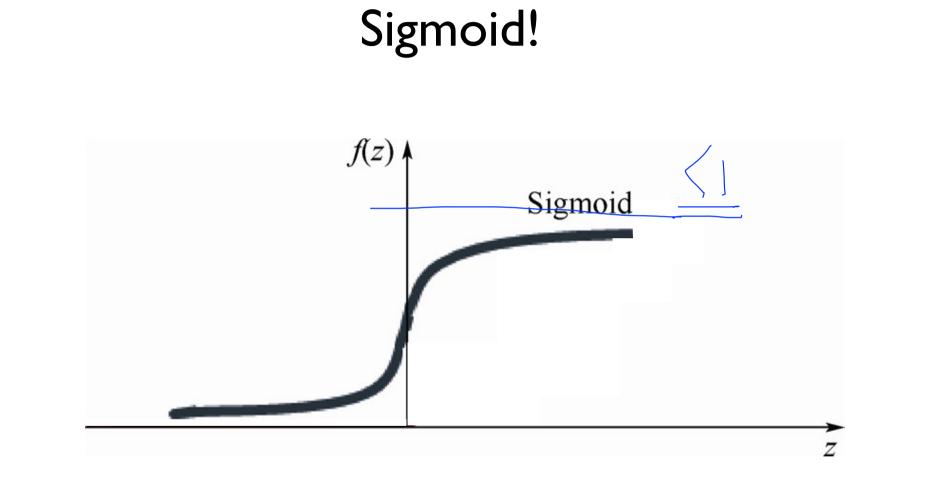


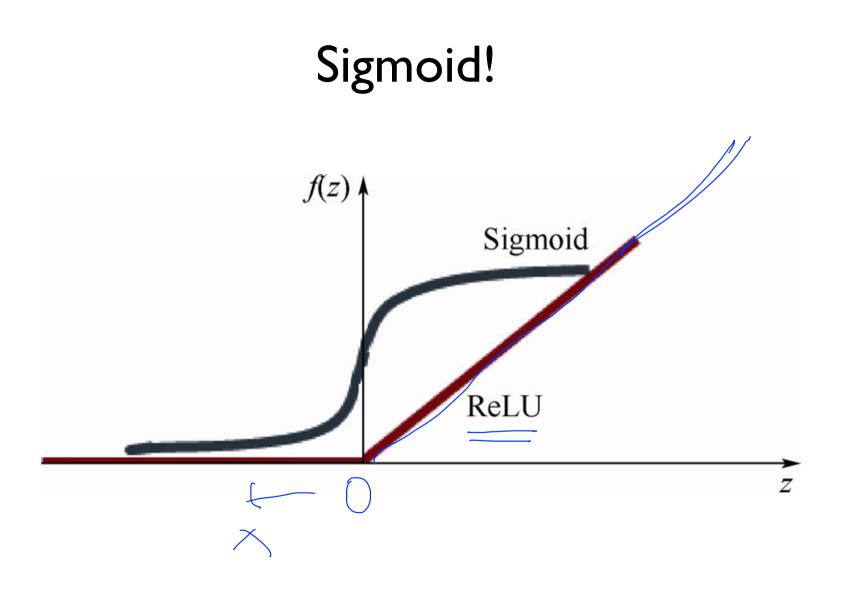


Geoffrey Hinton's summary of findings up to today

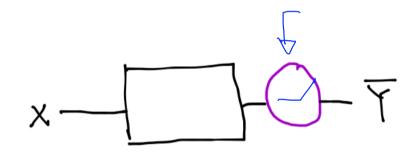
- Our labeled datasets were thousands of times too small.
- Our computers were millions of times too slow.
- We initialized the weights in a stupid way.
- We used the wrong type of non-linearity.

http://www.andreykurenkov.com/writing/a-brief-history-of-neural-nets-and-deep-learning-part-4/





ReLU: Rectified Linear Unit



ReLU: Rectified Linear Unit mox(0, x)



 $L1 = \frac{\text{tf.sigmoid}}{\text{tf.matmul}(X, W1) + b1}$

L1 = tf.nn.relu(tf.matmul(X, W1) + b1)

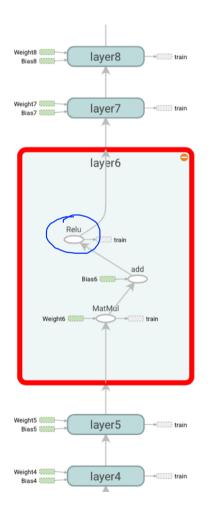
ReLu

Our hypothesis with tf.name_scope("layer1") as scope: L1 = tf.nn.relu(tf.matmul(X, W1) + b1)with tf.name_scope("layer2") as scope: L2 = tf.nn.relu(tf.matmul(L1, W2) + b2)with tf.name_scope("layer3") as scope: L3 = tf.nn.relu(tf.matmul(L2, W3) + b3)with tf.name scope("layer4") as scope: L4 = tf.nn.relu(tf.matmul(L3, W4) + b4)with tf.name scope("layer5") as scope: L5 = tf.nn.relu(tf.matmul(L4, W5) + b5)with tf.name_scope("layer6") as scope: L6 = tf.nn.relu(tf.matmul(L5, W6) + b6)with tf.name_scope("layer7") as scope: L7 = tf.nn.relu(tf.matmul(L6, W7) + b7)with tf.name_scope("layer8") as scope: L8 = tf.nn.relu(tf.matmul(L7, W8) + b8)with tf.name scope("layer9") as scope: L9 = tf.nn.relu(tf.matmul(L8, W9) + b9)with tf.name_scope("layer10") as scope: L10 = tf.nn.relu(tf.matmul(L9, W10) + b10)with tf.name_scope("last") as scope: hypothesis = tf.sigmoid(tf.matmul(L10, W11) + b11)

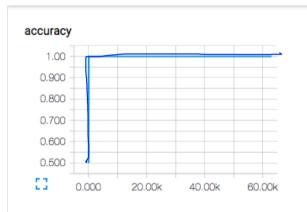
Works very well

```
196000 [2.6226094e-06, array([[ 2.59195826e-06],
       [ 9.99999642e-01],
       [ 9.99994874e-01],
       [ 2.43454133e-06]], dtype=float32)]
198000 [2.607708e-06, array([[ 2.55822852e-06],
       [ 9.99999642e-01],
       [ 9.99994874e-01],
      [ 2.40260101e-06]], dtype=float32)]
[array([[ 2.52509381e-06],
       [ 9.99999642e-01],
       [ 9.99994874e-01],
       [ 2.37124709e-06]], dtype=float32), array([[ 0.],
       [ 1.],
       [ 1.],
       [ 0.]], dtype=float32)]
Accuracy: 1.0
```

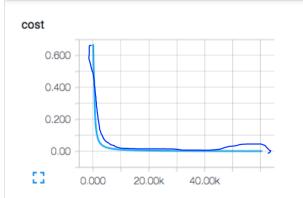
Works very well

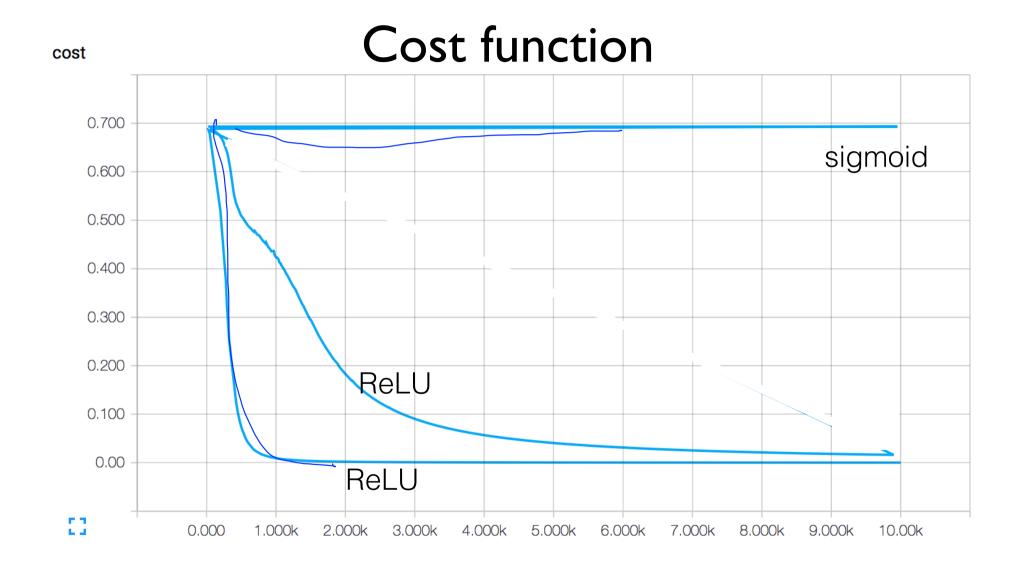


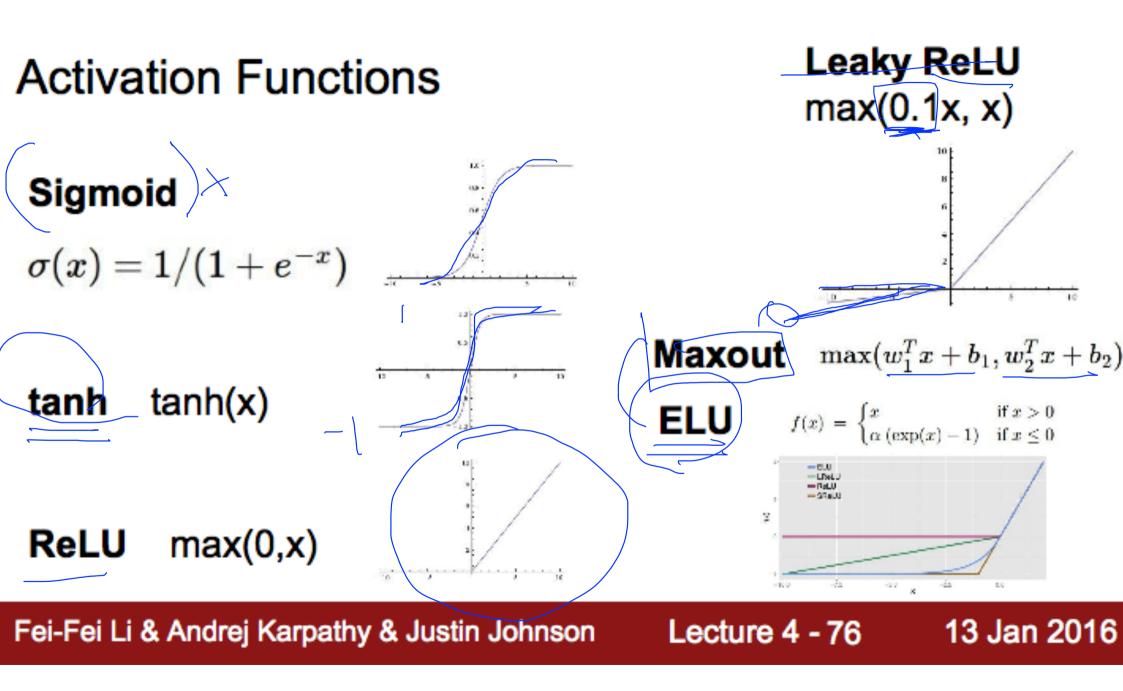




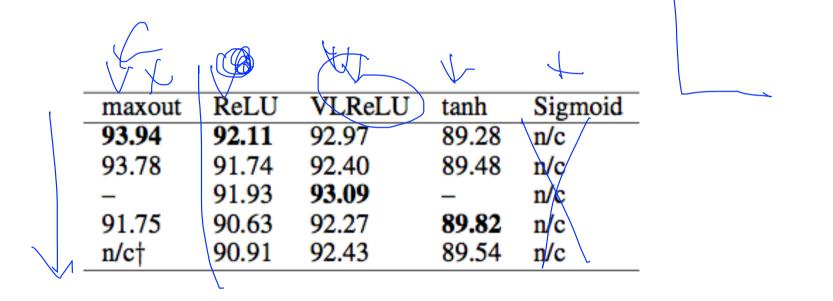
cost



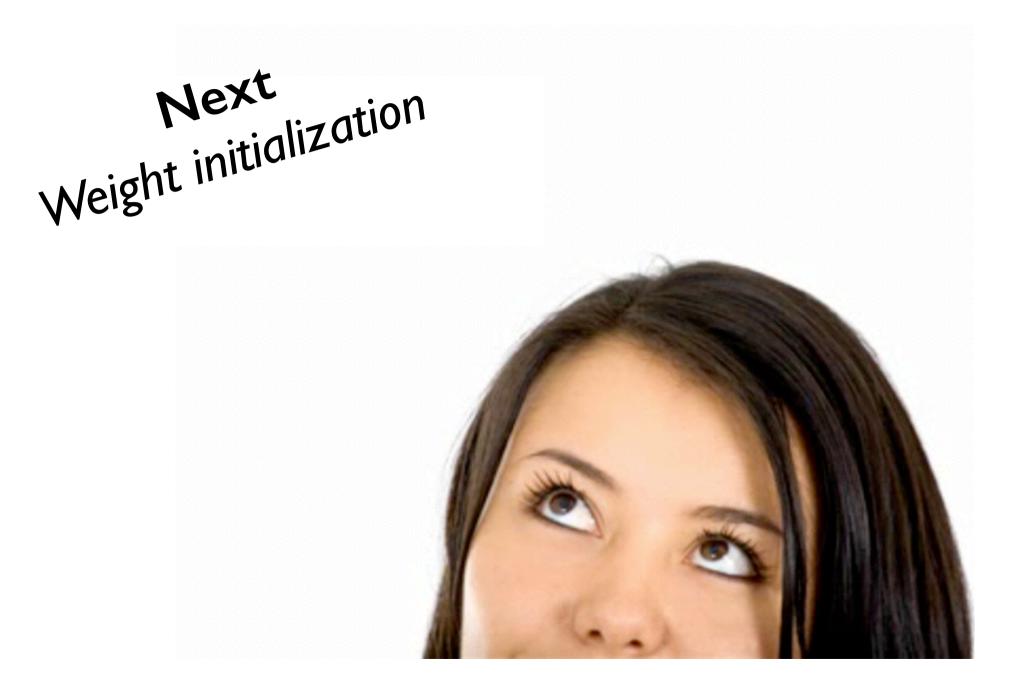




Activation functions on CIFAR-10



[Mishkin et al. 2015]

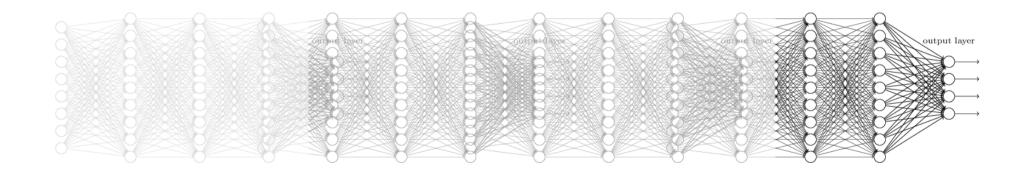


Lecture 10-2

Initialize weights in a smart way

Sung Kim <hunkim+mr@gmail.com> http://hunkim.github.io/ml/

Vanishing gradient

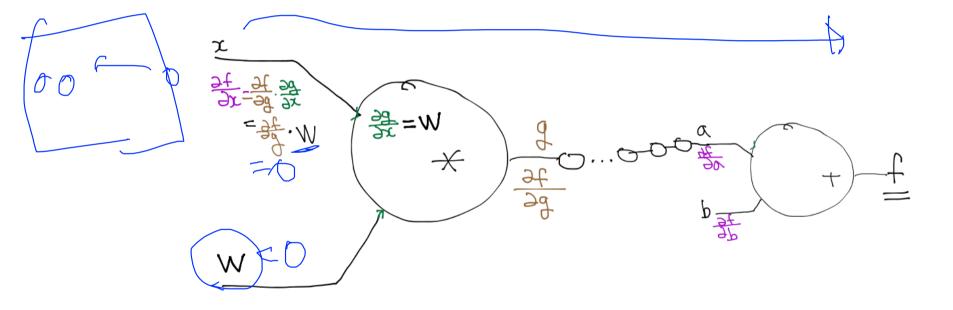


Geoffrey Hinton's summary of findings up to today

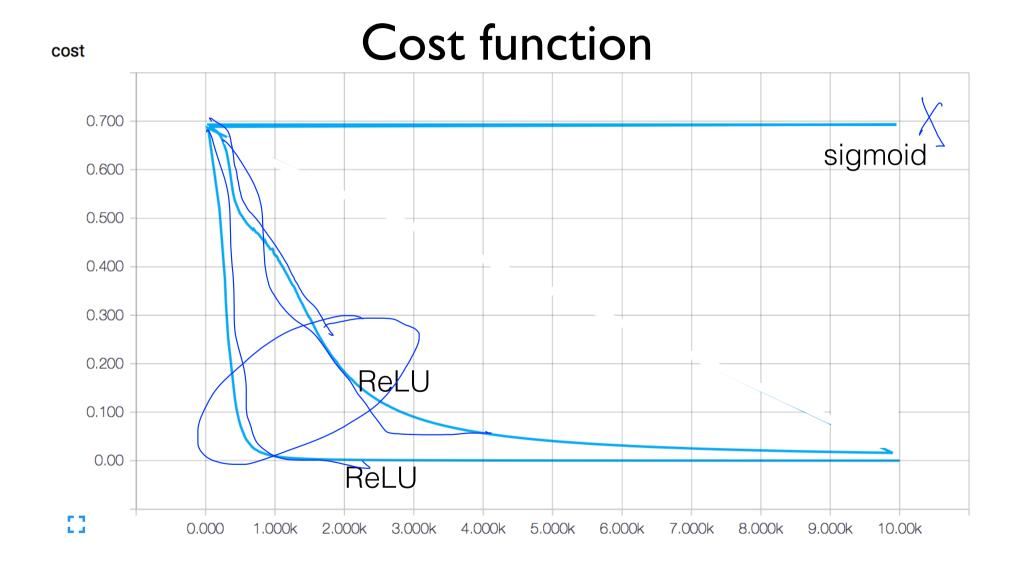
- Our labeled datasets were thousands of times too small.
- Our computers were millions of times too slow.
- We initialized the weights in a stupid way.
- We used the wrong type of non-linearity.

http://www.andreykurenkov.com/writing/a-brief-history-of-neural-nets-and-deep-learning-part-4/

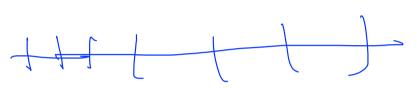




http://cs231n.stanford.edu/

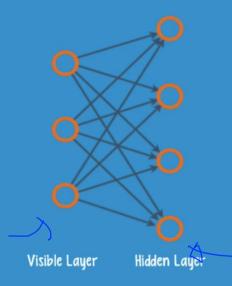


Need to set the initial weight values wisely



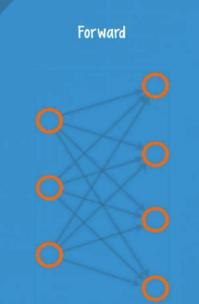
- Not all 0's
- Challenging issue
- Hinton et al. (2006) "A Fast Learning Algorithm for Deep Belief Nets"
 - Restricted Boatman Machine (RBM)

RBM STRUGTURE



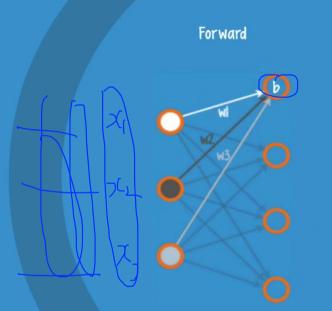
RESTRICTION = NO CONNECTIONS WITHIN A LAYER





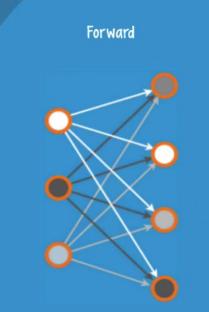
Backward





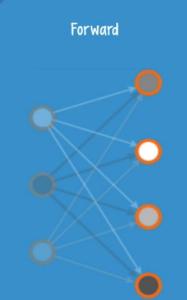


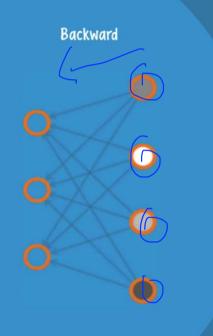














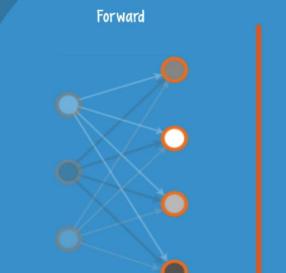
REGREATE INPUT Forward Backward



REGREATE INPUT Forward Backward

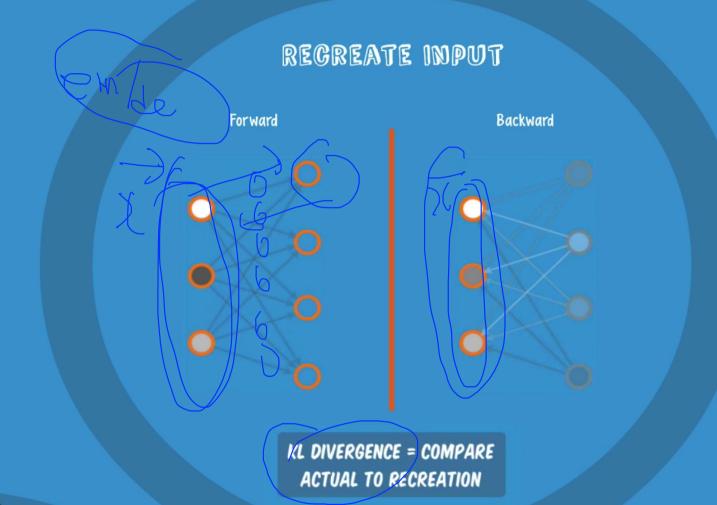


REGREATE INPUT



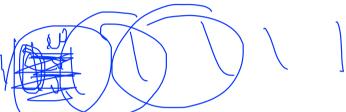




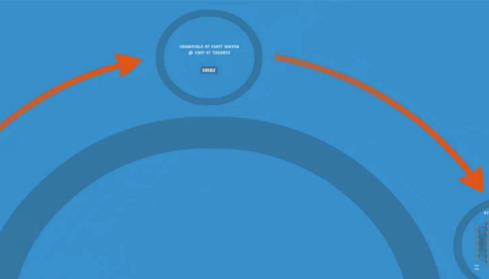




How can we use RBM to initialize weights?



- Apply the RBM idea on adjacent two layers as a pre-training step
- Continue the first process to all layers
- This will set weights
- Example: Deep Belief Network
 - Weight initialized by RBM



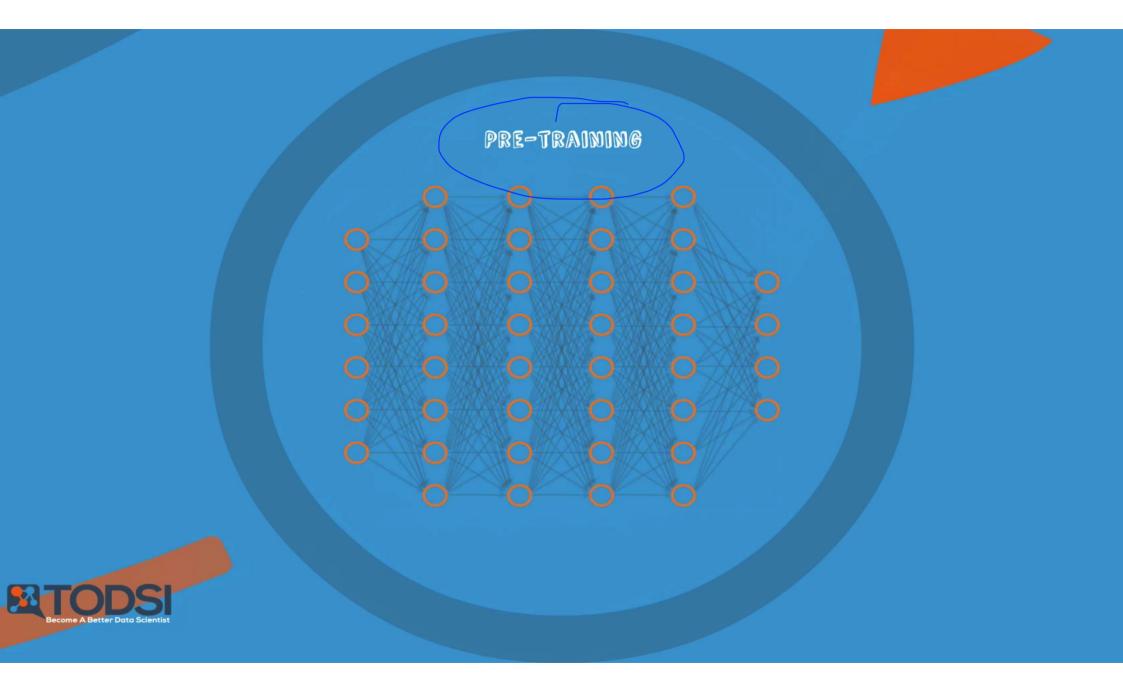
deep belief network (dbn)

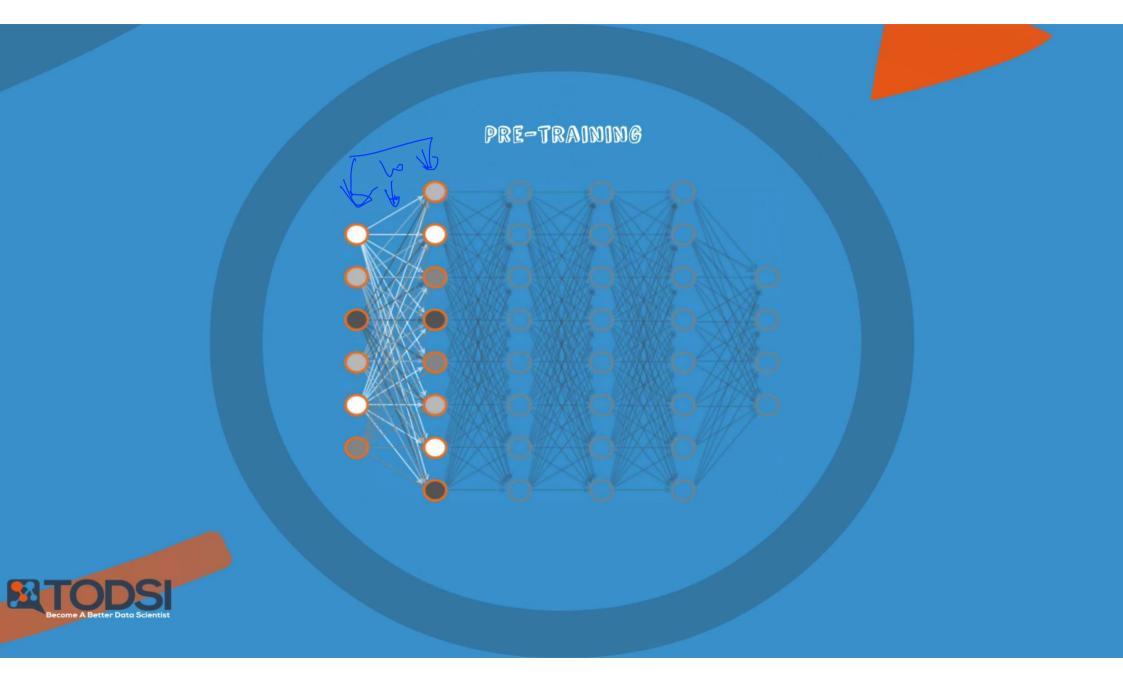
Unsupervised, layer-wise, greedy pre-training

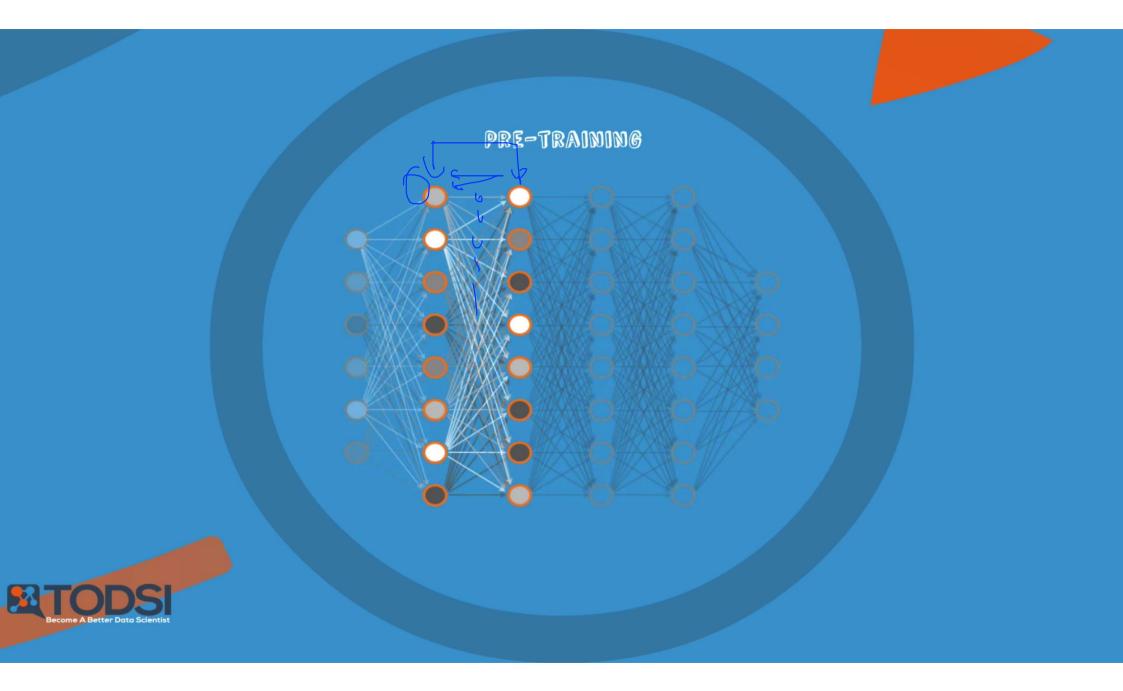


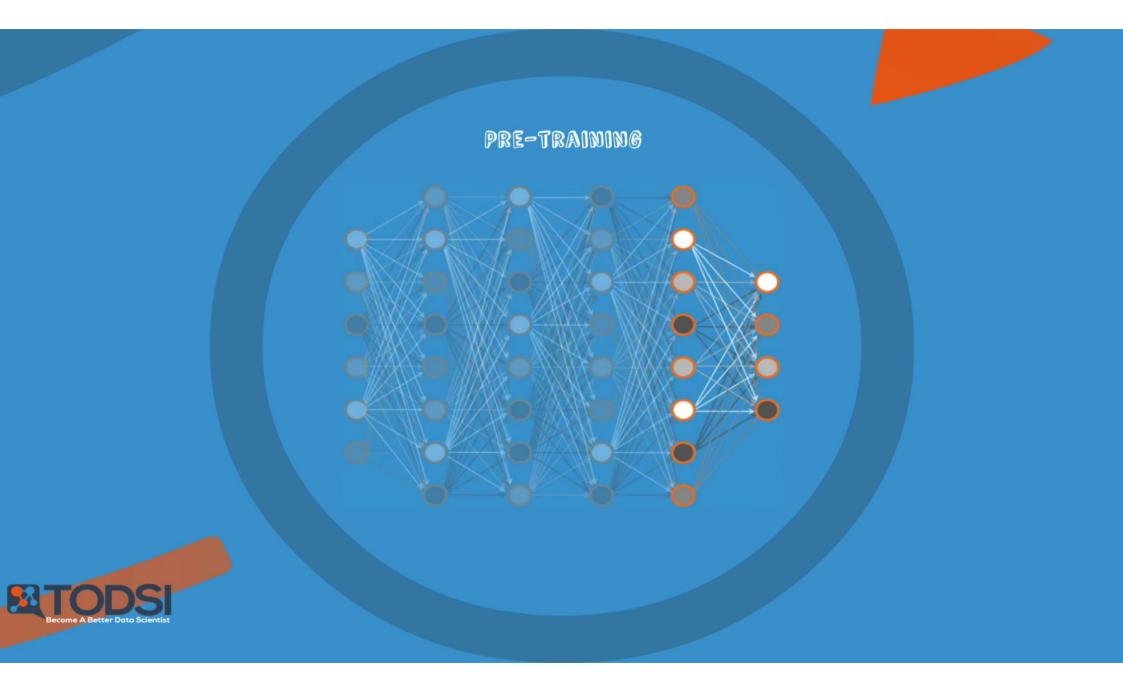
R

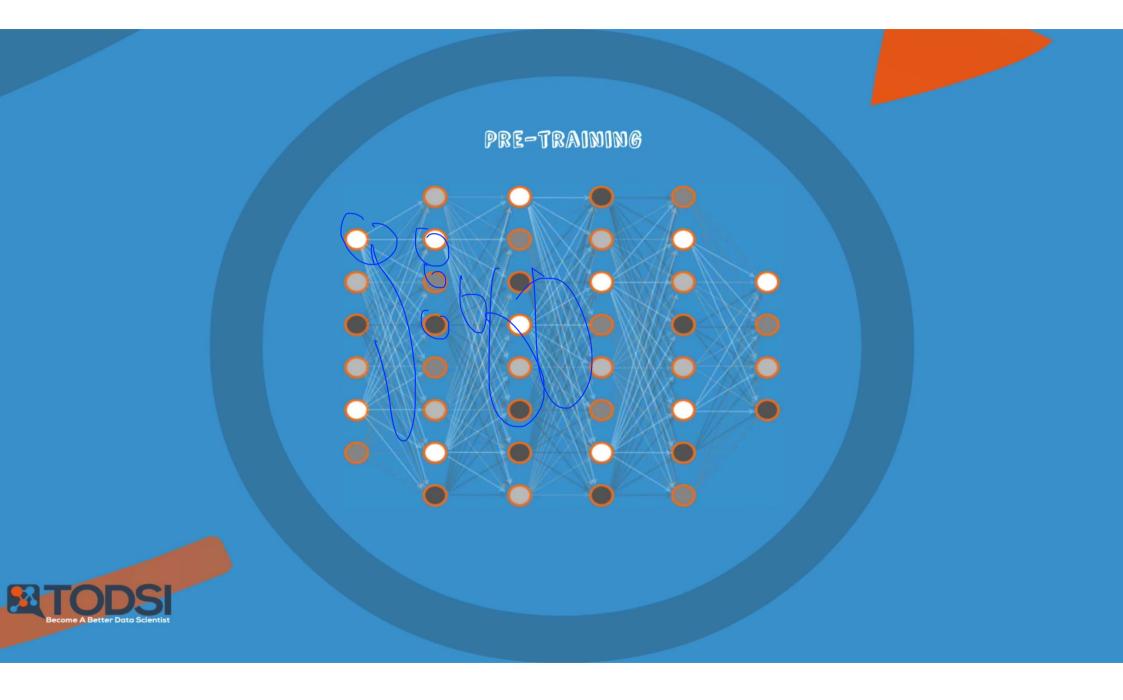
NAL CARGO

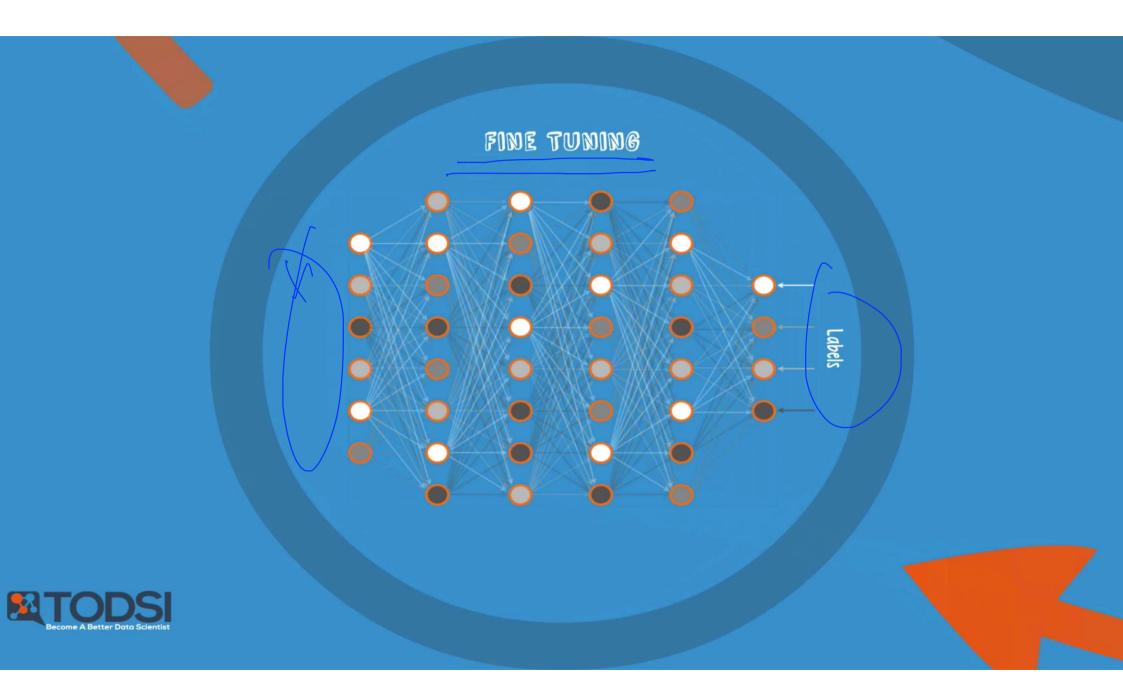












Good news



- No need to use complicated RBM for weight initializations
- Simple methods are OK
 - Xavier initialization: X. Glorot and Y. Bengio, "Understanding the difficulty of training deep feedforward neural networks," in International conference on artificial intelligence and statistics, 2010
 - He's initialization: K. He, X. Zhang, S. Ren, and J. Sun, "Delving Deep into Rectifiers: Surpassing Human-Level Performance on ImageNet Classification," 2015

Xavier/He initialization

- Makes sure the weights are 'just right', not too small, not too big
- Using number of input (fan_in) and output (fan_out)

Xavier initialization Glorot et al. 2010 fan_out//np.sqrt(fan_in) = np.random.randn(fan_in, 2015 et al. = np.random.randn(fan_in, fan_out)/np.sqrt(fan_in/2) W

http://cs231n.stanford.edu/

prettytensor implementation

```
def xavier init(n inputs, n outputs, uniform=True):
  """Set the parameter initialization using the method described.
 This method is designed to keep the scale of the gradients roughly the same
 in all layers.
 Xavier Glorot and Yoshua Bengio (2010):
           Understanding the difficulty of training deep feedforward neural
           networks. International conference on artificial intelligence and
           statistics.
 Args:
   n inputs: The number of input nodes into each output.
    n outputs: The number of output nodes for each input.
    uniform: If true use a uniform distribution, otherwise use a normal.
  Returns:
    An initializer.
  .....
  if uniform:
   # 6 was used in the paper.
   init_range = math.sqrt(6.0 / (n_inputs + n_outputs))
    return tf.random_uniform_initializer(-init_range, init_range)
  else:
   # 3 gives us approximately the same limits as above since this repicks
   # values greater than 2 standard deviations from the mean.
   stddev = math.sqrt(3.0 / (n_inputs + n_outputs))
    return tf.truncated_normal_initializer(stddev=stddev)
```

http://stackoverflow.com/questions/33640581/how-to-do-xavier-initialization-on-tensorflow

Activation functions and initialization on CIFAR-10

Init method	maxout	ReLU	VLReLU	tanh	Sigmoid
LSUV	<u>93.94</u>	92.11	92.97	89.28	n/c
└ OrthoNorm	93.78	91.74	92.40	89.48	n/c
OrthoNorm-MSRA scaled	_ /	91.93	93.09	_	n/c
Xavier	91.75	90.63	92.27	89.82	n/c
MSRA	n/c†	90.91	92.43	89.54	n/c

[Mishkin et al. 2015]

Still an active area of research

- We don't know how to initialize perfect weight values, yet
- Many new algorithms
 - Batch normalization

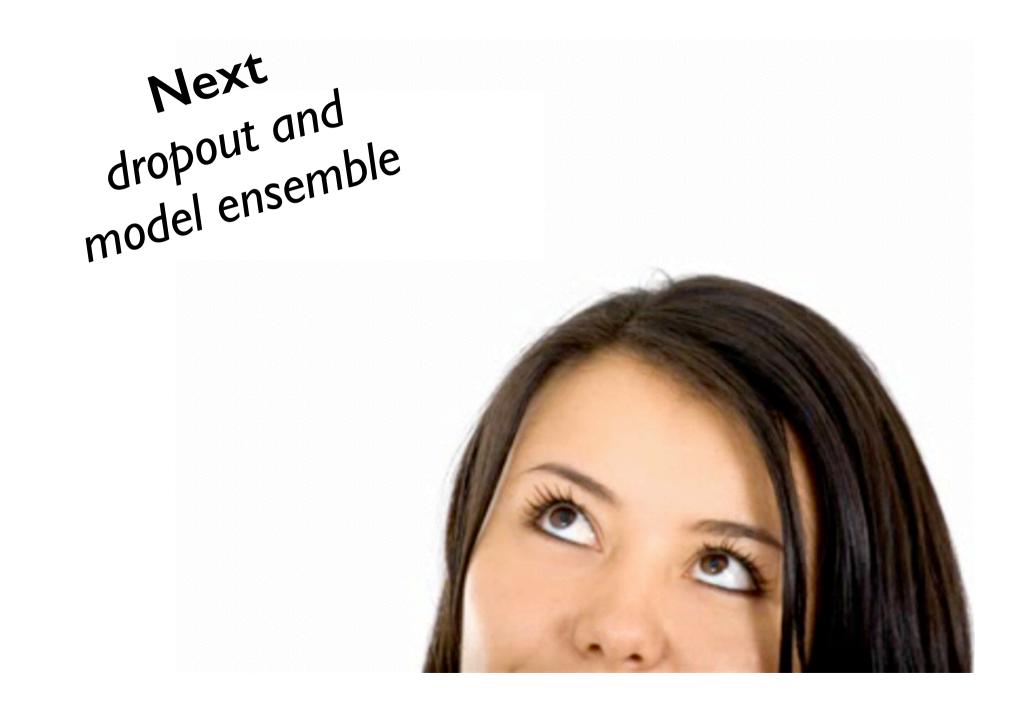
. . .

- Layer sequential uniform variance

Geoffrey Hinton's summary of findings up to today

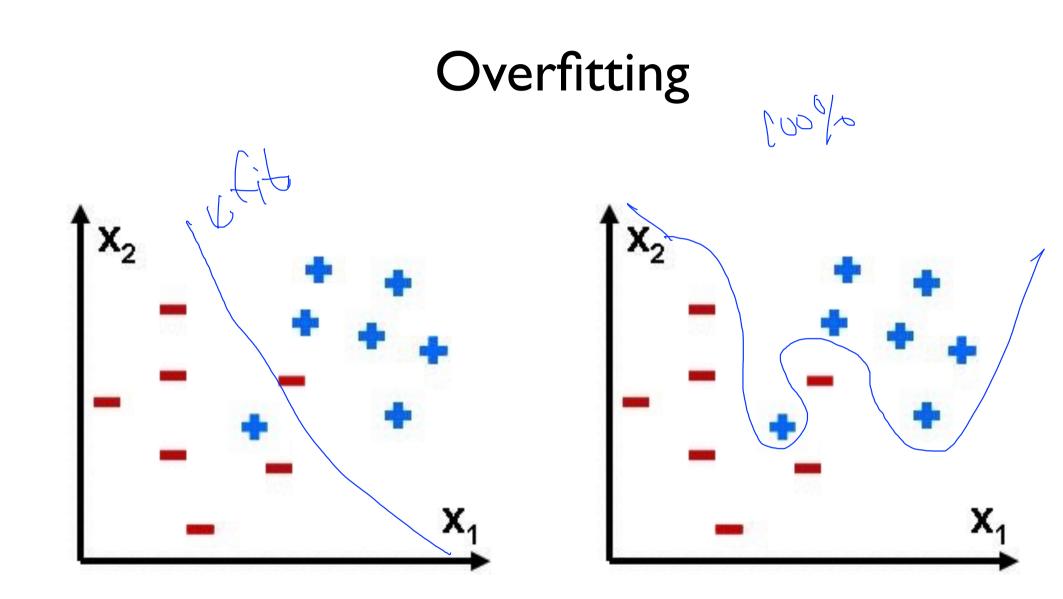
- Our labeled datasets were thousands of times too small.
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- ullet We used the wrong type of non-linearity. \bigvee

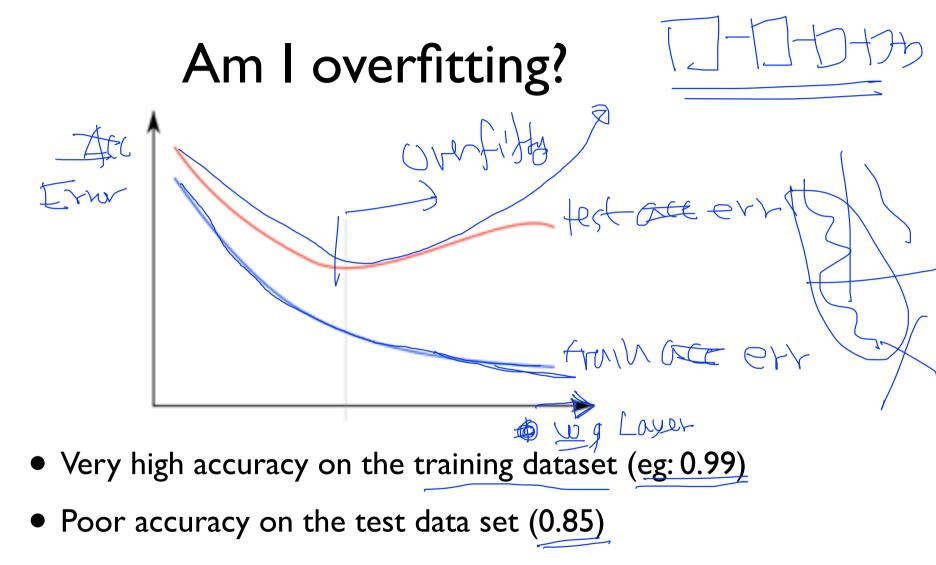
http://www.andreykurenkov.com/writing/a-brief-history-of-neural-nets-and-deep-learning-part-4/



Lecture 10-3 NN dropout and model ensemble

Sung Kim <hunkim+mr@gmail.com>

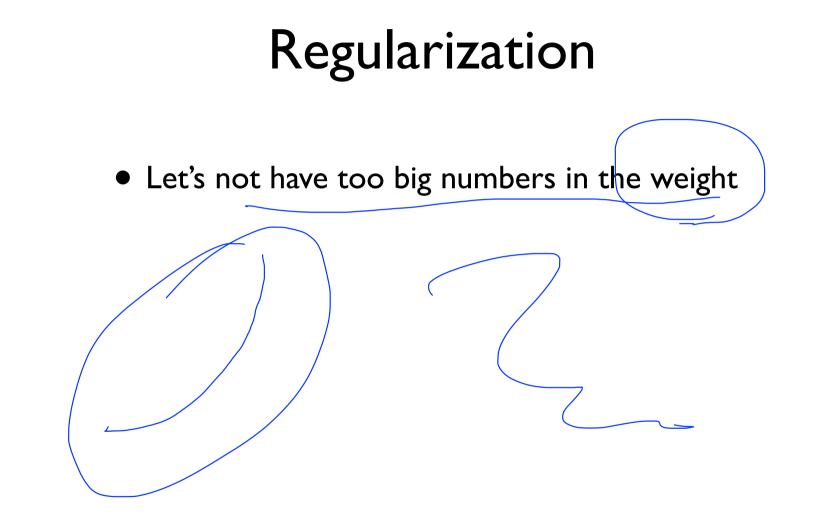


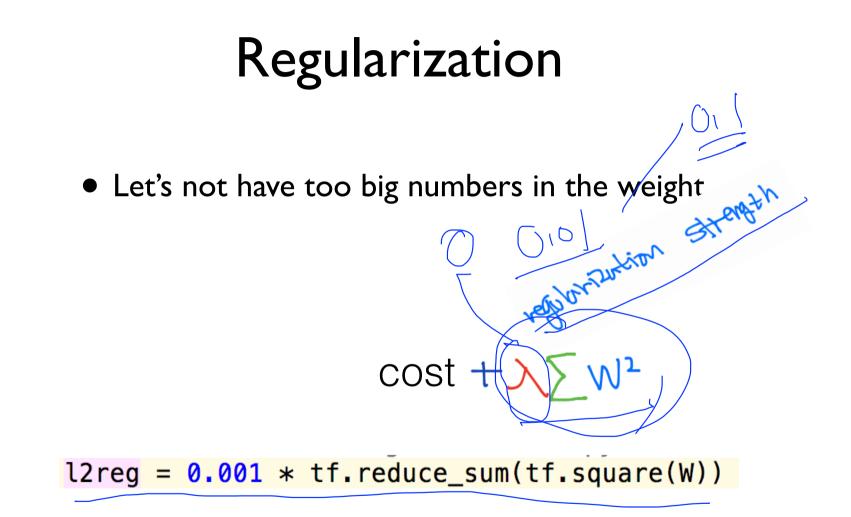


http://cs224d.stanford.edu/syllabus.html

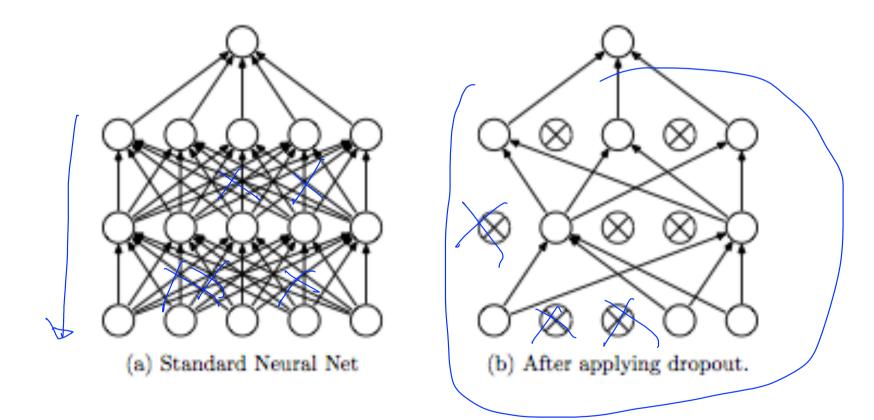
Solutions for overfitting

- More training data!
- Reduce the number of features
- Regularization



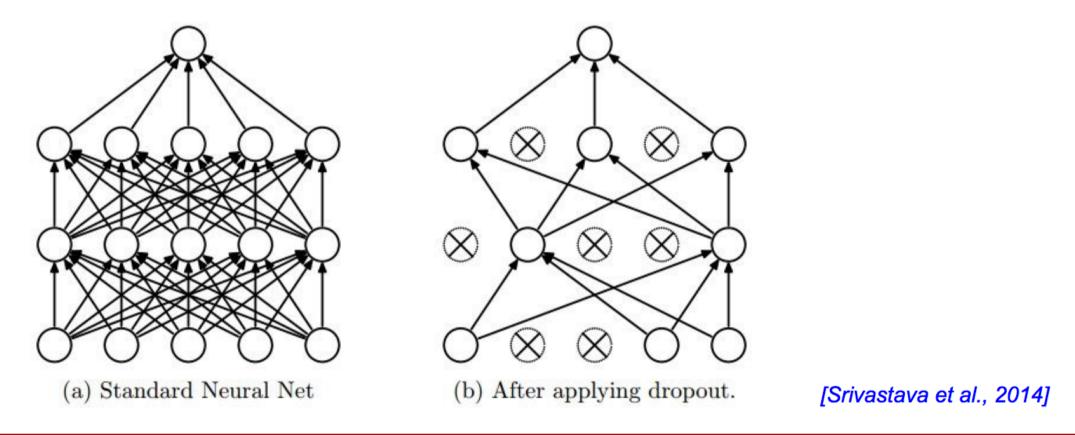


Dropout: A Simple Way to Prevent Neural Networks from Overfitting [Srivastava et al. 2014]



Regularization: **Dropout**

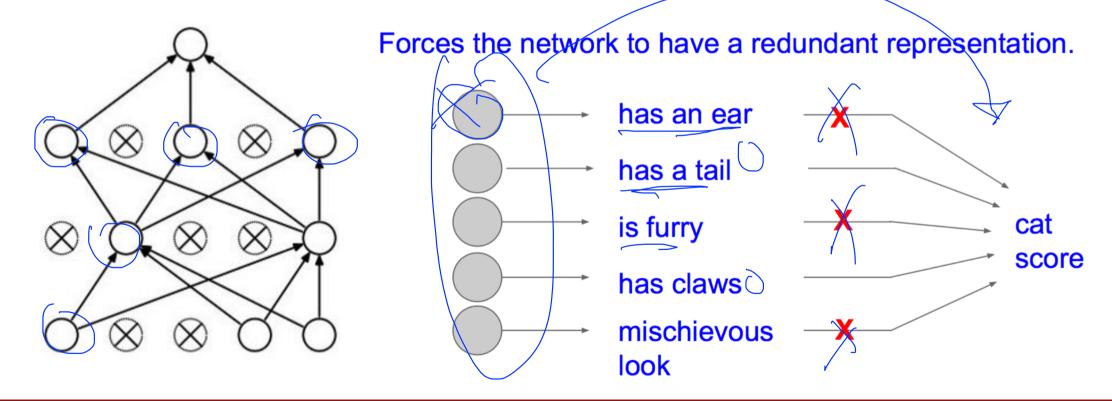
"randomly set some neurons to zero in the forward pass"



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Waaaait a second... How could this possibly be a good idea?

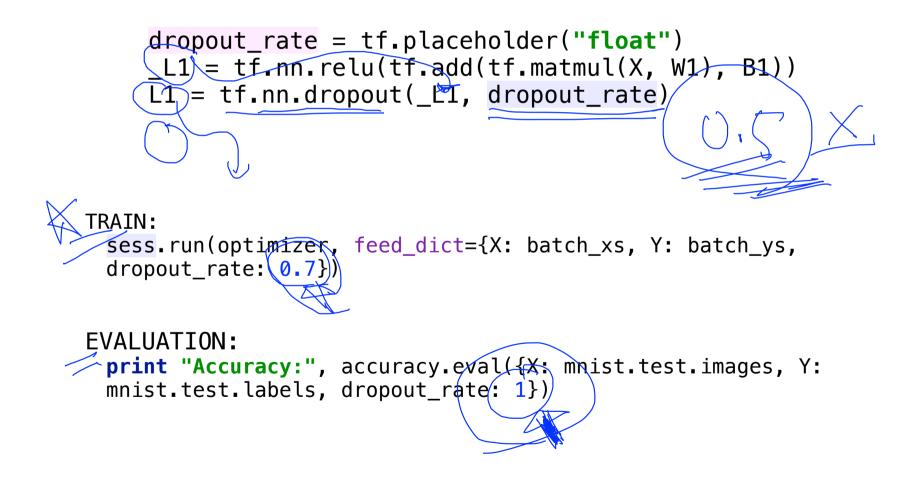


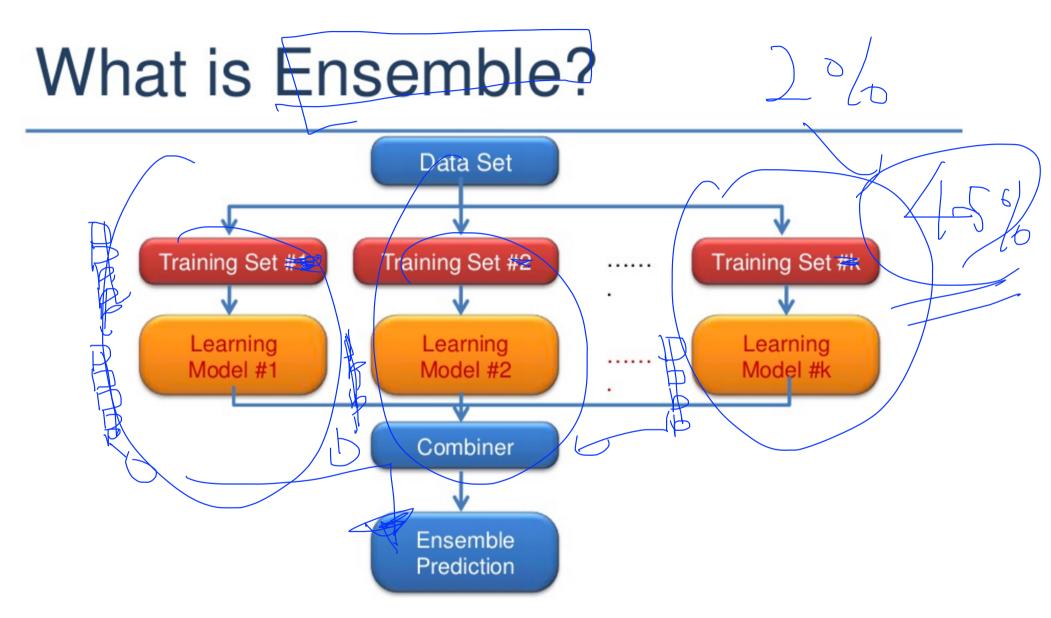
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25 Jan 2016

TensorFlow implementation

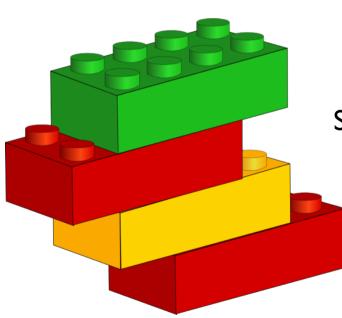




http://www.slideshare.net/sasasiapacific/ipb-improving-the-models-predictive-power-with-ensemble-approaches

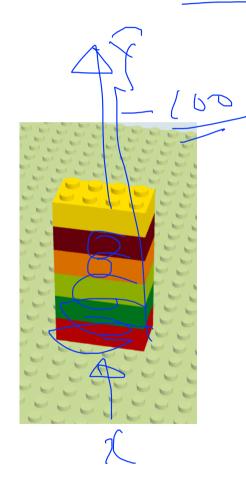


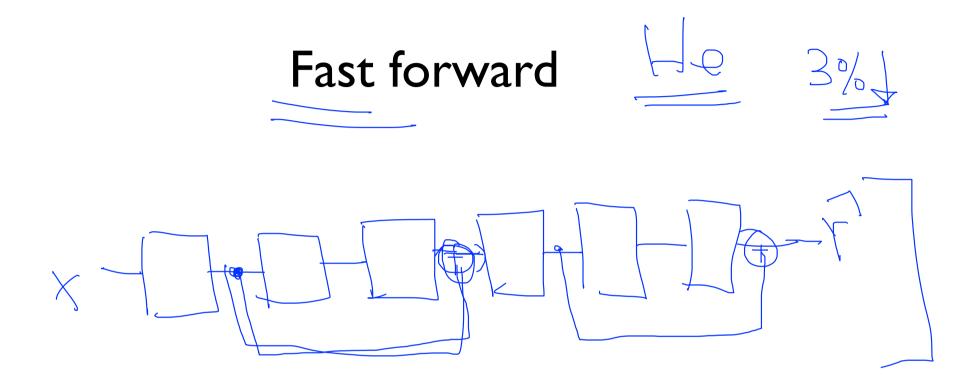
Lecture 10-4 NN LEGO Play

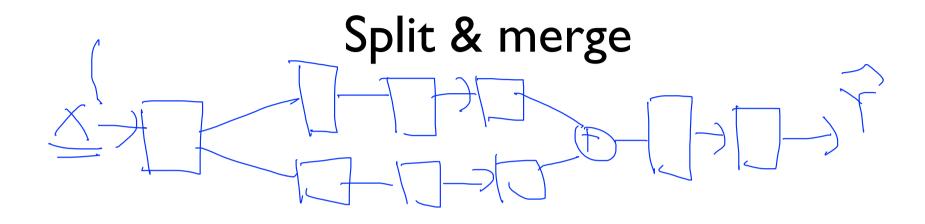


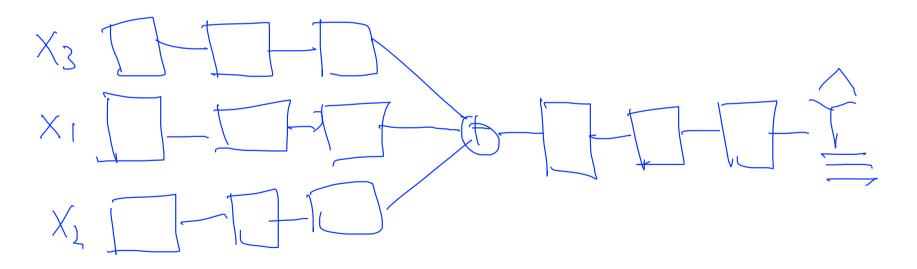
Sung Kim <hunkim+mr@gmail.com>

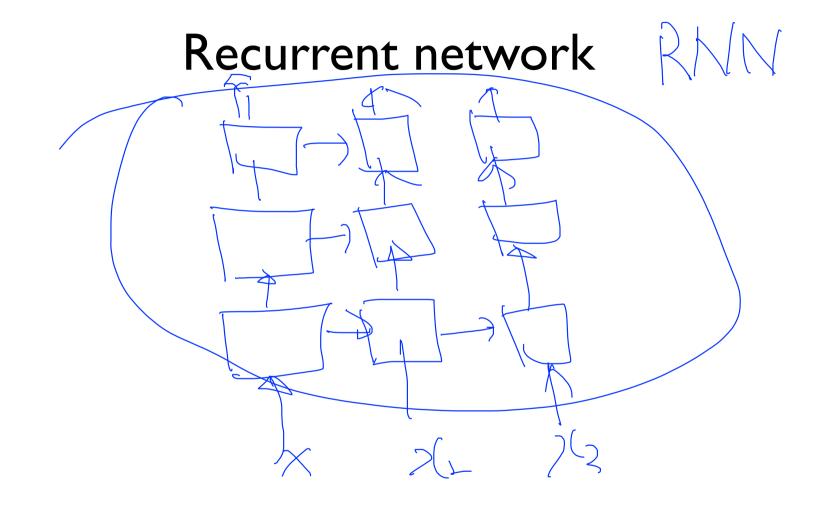
Feedforward neural network



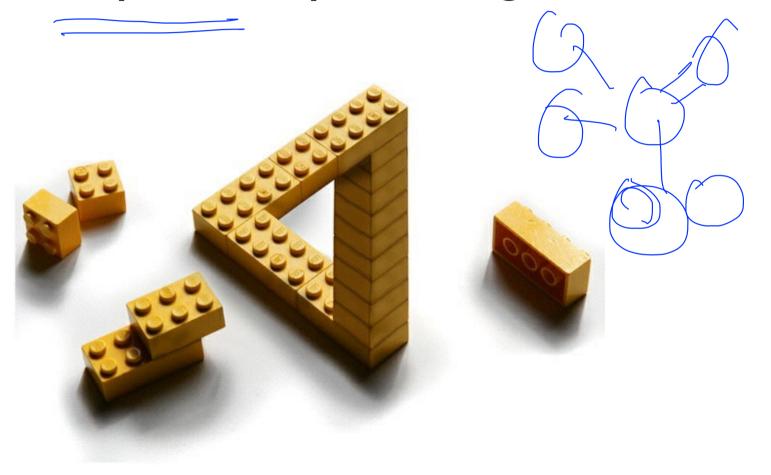








'The only limit is your imagination'



http://itchyi.squarespace.com/thelatest/2012/5/17/the-only-limit-is-your-imagination.html